Technische Universität Nürnberg

# UTN

## Master of Science (M.Sc.) Artificial Intelligence and Robotics

**Module Handbook** 

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#### 1. Overview

Artificial intelligence (AI) is a rapidly growing field that is changing the way we live and work. As a result, there is a growing demand for professionals with experience in robotics and artificial intelligence in various industries.

The Master's in Artificial Intelligence and Robotics degree program provides students with the opportunity to develop advanced skills and knowledge in these exciting fields. By combining theoretical and practical courses with our new learning design, students will gain an in-depth understanding of the concepts, algorithms, and applications of robotics and AI. They also learn to design, implement, and evaluate complex robotic systems and AI algorithms.

Graduates of the program are equipped to pursue careers in a variety of industries, including manufacturing, healthcare, transportation, and entertainment. They are also ready to pursue research and academic opportunities in robotics and artificial intelligence.

Our innovative teaching and learning approach, rooted in extensive research, emphasizes active engagement and reflective practices. Rather than memorization-based learning, our approach entails students undertaking learning-oriented assignments throughout the semester and receiving personalized feedback from faculty on their progress.

The scientific core will be the essential content of the program. In the case of M.Sc. Artificial Intelligence and Robotics, the following six basic modules serve as your scientific core.

- 1. Artificial Intelligence
- 2. Mobile Robot Navigation
- 3. Machine Learning
- 4. Computer Vision
- 5. Deep Learning
- 6. Data Science

The curriculum of this master's program is a modular study program. Students will learn about problem solving, decision making, and knowledge representation in AI as well as the design and implementation of algorithms for autonomous robot navigation. They will study neural networks, training algorithms, optimization techniques, and applications in computer vision and natural language processing. Students will also learn about data analysis, statistical methods, data visualization, and data mining techniques. Through practical assignments and projects, they will gain hands-on experience in designing and implementing algorithms and systems in these fields. The unique highlight of this program is the learning in transformation project, an interdisciplinary scientific research project that focuses on practical learning experiences. The project aims to provide students with a scientific-based approach to solving real-world problems.

#### 2. Learning Outcomes

**Goal 1**: Provide students theory-grounded and science-based content and methods for the innovative, effective, and sustainable design or development of technologies for AI and robotics systems.

*Objective 1.1:* Students are able to understand advanced fundamental approaches in Artificial Intelligence (AI) and robotics, including machine learning, computer vision, and data science.

*Objective 1.2:* Students are able to articulate and differentiate their knowledge from different domains regarding innovative ideas.

*Objective 1.3:* Students are able to critically reflect on limitations of state-of-the-art approaches.

**Goal 2**: Provide students with scientific experiences (e.g., content, methods, assignments) to develop and apply skills in data collection, analysis, and evaluation for AI and robotics systems.

*Objective 2.1:* Students are able to apply state-of-the-art methods to given problems and existing datasets.

*Objective 2.2:* Students are able to scientifically analyze AI approaches.

*Objective 2.3:* Students are able to combine their knowledge from different domains to identify innovative solutions.

**Goal 3**: Provide students with scientific experiences to create novel solutions using AI or robotics technologies in response to current and future challenges of emerging technologies.

*Objective 3.1:* Students are able to create novel AI or robotic systems that extend the current capabilities of such systems.

*Objective 3.2:* Students are able to evaluate the consequences of the application of AI and robotics approaches on spheres outside their own core area of expertise and make appropriate adaptations.

**Goal 4:** Provide students content and methods grounded in theory and science from complementary academic fields to critically reflect on AI and robotic approaches and their consequences.

*Objective 4.1:* Students are able to understand fundamental approaches in selected fields of social sciences or humanities.

*Objective 4.2:* Students are able to combine knowledge from different academic fields to evaluate AI and robotics approaches.

#### Goal 5:

- Provide students with techniques to work effectively in diverse teams and continuously develop their own expertise and learning.
- Provide students with the abilities needed to practice sustainability and democratic citizenship.
- Enable students to reflect on and relate their own actions to social and ethical contexts.

*Objective 5.1:* Students are able to appropriately coordinate, cooperate, and communicate with the target group.

*Objective 5.2:* Students are able to demonstrate effective problem solving and critical thinking skills in resolving job-related issues.

*Objective 5.3*: Students are able to utilize adaptive expertise and pursue creativity and lifelong learning.

*Objective 5.4:* Students are able to embrace the values of a democratic society and a sustainable environment and act accordingly.

*Objective 5.5:* Students are able to reflect on technology leadership and knowledge of ethics and relate them to current and future sociotechnical contexts.

#### 3. Study Program Outline

AIR: Artificial Intelligence (AI) and Robotics (R)

	Module	ECTS	Associated courses
	Artificial Intelligence Basic Module	6	Artificial Intelligence
Mandatory	Mobile Robot Navigation Basic Module	6	Mobile Robot Navigation
nda	Machine Learning Basic Module	6	Machine Learning
Ra	Deep Learning Basic Module	6	Deep Learning
	Computer Vision Basic Module	6	Computer Vision
	Data Science Basic Module	6	Data Science
	Advanced Module 1	6	All advanced AIR courses
s.	Advanced Module 2	6	Students select one advanced AI course
Elective	Advanced Module 3	6	course per module. (We recommend finishing the base module before beginning the advanced module.)
Mandatory	Learning in Transformation Project	12	Learning in Transformation Project
Ň	Key Qualification (KQ) Basic Module	6	Good Scientific Practice, Project Management, Communication
	Key Qualification Module 1	6	All KQ courses Students select KQ courses that provide
ive	Key Qualification Module 2	6	a total of 6 ECTS points (usually 2-3 courses) per module.
Elective	Interdisciplinary (ID) Module 1	6	All ID courses Students select one ID course per
	Interdisciplinary Module 2	6	module.
	Master's Thesis	24	Master's Thesis and Colloquium

*Note.* ECTS = European Credit Transfer System

### 4. Recommended Study Plan

Sem.					
1	Artificial Intelligence Basic (mandatory)	Mobile Robot Navigation (mandatory)	Machine Learning (mandatory)	Data Science (mandatory)	Key Qualification Basic Module (mandatory)
2	Deep Learning (mandatory)	Computer Vision (mandatory)	Interdiscipli- nary Module 1	Key Qualification Module 1	Learning in Transformation
3	Advanced Module 1	Advanced Module 2	Advanced Module 3	Key Qualification Module 2	(Project)
4	Interdiscipli- nary Module 2	Master's Thesis (Colloquium + Thesis)			

#### 5. Modules

5.1 Artificial Ir	ntelligenc	e Basic	Module	6 ECTS
Recommended semester	1 <sup>st</sup> semest	er	Total workload	180 hours
Module number		1-M-AIR-AI	B-1	
Duration		One semes	ter	
Course frequency		Winter sem	nester	
Module language		English		
Prerequisites		None		
Associated courses		Artificial Ir	ntelligence	
Instructor		Prof. Dr. Wo	olfram Burgard	
Examination		Learning-o	riented assignments	
Grading		Graded		
Learning outcomes		<ul> <li>Students are able to</li> <li>describe different approaches to define artificial intelligence;</li> <li>classify different types of problems, environments, and intelligent agents;</li> <li>formulate problems as search problems and apply different algorithms to solve them;</li> <li>explain basic concepts of first-order and predicate logic;</li> <li>apply basic approaches to probabilistic reasoning an decision making under uncertainty;</li> <li>identify advanced concepts of AI; and</li> <li>assess ethical consequences of AI and its application and discuss interdisciplinary aspects of AI.</li> </ul>		
Content		<ul> <li>The content of this module is mainly based on the content of the textbook by Stuart Russell and Peter Norvig, Artificial Intelligence: A Modern Approach, Chapters 1-4. The book is available in the library.</li> <li>Approaches to AI</li> <li>Problem solving using AI</li> <li>Knowledge, reasoning, and planning in AI</li> <li>Probabilistic reasoning</li> </ul>		
Teaching and learning	formats	See syllabı	JS	
Related programs		M.Sc. Al an	d Robotics	

5.2 Mobile Robo	ot Navig	gation Ba	asic Module	6 ECTS	
Recommended semester	1 <sup>st</sup> semes	ter	Total workload	180 hours	
Module number		1-M-AIR-M	IRB-1		
Duration		One seme	ster		
Course frequency		Winter ser	nester		
Module language		English			
Prerequisites		None			
Associated courses		Mobile Ro	bot Navigation		
Instructor		Prof. Dr. W	olfram Burgard		
Examination		Learning-o	oriented assignmen	ts	
Grading		Graded			
Learning outcomes		<ul> <li>Students are able to</li> <li>explain basic approaches to probabilistic senso and motion models as well as state estimation;</li> <li>compare basic approaches to robot localization robot mapping, simultaneous localization and mapping, motion and path planning, and exploration;</li> <li>design basic architectures for vehicles that navigate autonomously in complex environment</li> <li>identify advanced concepts of mobile robotics; and</li> <li>assess ethical consequences of robotics and its application and discuss interdisciplinary aspect</li> </ul>			
Content		<ul> <li>Probabilistic sensor and motion models</li> <li>Robot localization</li> <li>Robot mapping</li> <li>Simultaneous localization and mapping</li> <li>Motion and path planning and exploration</li> </ul>			
Teaching and learning	g formats	See syllabus			
Related programs		M.Sc. Al a	nd Robotics		

5.3 Machine Learning Basic Module 6 ECTS					
Recommended semester	1 <sup>st</sup> semest	ter	Total workload	180 hours	
Module number		1-M-AIR-M	ILB-1		
Duration		One seme	ster		
Course frequency		Winter ser	mester		
Module language		English			
Prerequisites		None			
Associated courses		Machine L	earning		
Instructor		NN (not kr	nown yet)		
Examination		Learning-o	priented assignmen	nts	
Grading		Graded			
Learning outcomes		<ul> <li>Students are able to</li> <li>explain basic approaches to supervised, unsupervised, and weakly supervised learning as well as reinforcement learning, gradient descent, and optimization;</li> <li>compare basic approaches to regression, classification, clustering, and principal component analysis;</li> <li>implement techniques for model selection and regularization;</li> <li>develop strategies to solve problems using machine learning approaches;</li> <li>identify advanced concepts of machine learning; and</li> <li>assess ethical consequences of machine learning and its application and discuss interdisciplinary aspects.</li> </ul>			
Content		<ul> <li>Supervised learning (regression and classification)</li> <li>Unsupervised learning (clustering, principal component analysis)</li> <li>Weakly supervised learning</li> <li>Model selection and regularization</li> </ul>			
Teaching and learning	formats	See syllabus			
Related programs		M.Sc. Al a	nd Robotics		

5.3 Data Scienc	e Basic	Module		6 ECTS	
Recommended semester	1 <sup>st</sup> semes	ter	Total workload	180 hours	
Module number		1-M-AIR-D	SB-1		
Duration		One seme	ster		
Course frequency		Winter ser	nester		
Module language		English			
Prerequisites		None			
Associated courses		Data Scier	nce		
Instructor		Prof. Dr. A	ndreas Kipf		
Examination		Learning-o	priented assignme	nts	
Grading		Graded			
Learning outcomes		<ul> <li>Students are able to</li> <li>explain basic approaches to data engineering and visualization;</li> <li>compare basic approaches to data cleaning and integration;</li> <li>design basic architectures for data processing systems and data pipelines;</li> <li>identify advanced concepts of data engineering; and</li> <li>assess ethical consequences of large data and its application and discuss interdisciplinary aspects.</li> </ul>			
Content		<ul> <li>Data engineering foundations</li> <li>Data cleaning</li> <li>Data integration</li> <li>Data processing systems</li> <li>Data pipelines</li> <li>Visualization</li> </ul>			
Teaching and learning	g formats	See syllabus			
Related programs		M.Sc. Al a	nd Robotics		

5.4 Computer	/ision B	asic Mo	dule	6 ECTS	
Recommended semester	2 <sup>nd</sup> semes	ster	Total workload	180 hours	
Module number		1-M-AIR-C	VB-1		
Duration		One seme	ster		
Course frequency		Summer s	emester		
Module language		English			
Prerequisites		None			
Associated courses		Computer	Vision		
Instructor		NN			
Examination		Learning-o	priented assignme	ents	
Grading		Graded			
Learning outcomes	<ul> <li>Students are able to</li> <li>explain the working principles of a digital camera;</li> <li>implement basic approaches to feature extraction, scene reconstruction, object detection and recognition, and pose and motion estimation;</li> <li>develop strategies to solve computer vision problems by using approaches based on deep learning;</li> <li>identify advanced concepts of computer vision;</li> </ul>				
			application and o	nces of computer vision liscuss interdisciplinary	
Content	<ul> <li>Working principles of a digital camera</li> <li>Feature extraction</li> <li>Scene reconstruction</li> <li>Object detection and recognition</li> <li>Pose and motion estimation</li> <li>Approaches to computer vision based on deep learning</li> </ul>				
Teaching and learning	g formats				
Related programs		-	nd Robotics		

5.5 Deep Learning Basic Module 6 ECTS					
Recommended semester	2 <sup>nd</sup> semester Total workload			180 hours	
Module number		1-M-AIR-R	LB-1		
Duration		One seme	ster		
Course frequency		Summer s	emester		
Module language		English			
Prerequisites		None			
Associated courses		Deep Lear	ning		
Instructor		Prof. Dr. W	olfram Burgard		
Examination		Learning-o	priented assignments		
Grading		Graded			
Learning outcomes		Students a	are able to		
		<ul> <li>feedforward networks, regularization for deep learning, and convolutional networks;</li> <li>explain recurrent recursive networks and practical aspects of deep learning;</li> <li>analyze deep learning approaches in the context of practical applications from computer vision, robotics, and related fields;</li> <li>implement techniques for model selection and regularization for deep learning;</li> <li>identify advanced concepts of deep learning; and assess ethical consequences of deep learning and its application and discuss interdisciplinary aspects.</li> </ul>			
Content		<ul> <li>Deep feedforward networks</li> <li>Regularization for deep learning</li> <li>Convolutional networks</li> <li>Recurrent recursive networks</li> <li>Practical aspects of deep learning</li> <li>Model selection and regularization for deep learning</li> </ul>			
Teaching and learnin	g formats				
Related programs		M.Sc. Al a	nd Robotics		

5.6 Advanced I	Module 1		6 ECTS		
Recommended semester	3 <sup>rd</sup> semester	Total workload	180 hours		
Module number	1-M-AIF				
Duration	One sei				
Course frequency		semester			
Module language	English				
Prerequisites	Associa	ated basic module	is recommended		
Associated courses			ted from all advanced AIR		
Instructor	Courses	s Is on selected cou	reo		
Examination		labus (varies by co			
Grading		-			
Learning outcomes		· · ·			
Content	Al a • dem und prin mac robo visio syst • ana • gen prob con • deve and • effe expo ider	<ul> <li>understanding of the fundamental concepts, principles, and theories in AI and robotics, such as machine learning, data science, deep learning, robotics, natural language processing, computer vision, reinforcement learning, and control systems;</li> <li>analyze and find solutions to a given problem;</li> <li>generate novel solutions and approaches to problems based on a concept or a combination of concepts presented in this course;</li> <li>develop proficiency in using state-of-the-art AI and robotics tools and platforms; and</li> <li>effectively reflect upon their knowledge and experiences in an interdisciplinary context by identifying connections between different disciplines and applying them in a meaningful</li> </ul>			
Content	knowle navigat learnin Studen course	<ul> <li>knowledge in up to three of the six fields of AI, robot navigation, deep learning, data science, machine learning, and computer vision.</li> <li>Students select one course from the advanced course offerings.</li> <li>The syllabus outlines the specific course content.</li> </ul>			
Teaching and learnin			· · · · · · · · · · · · · · · · · · ·		
Related programs		I and Robotics			

5.7 Advanced Module 2 6 ECTS					
Recommended semester	3 <sup>rd</sup> semester	Total workload	180 hours		
Module number	1-M-AIR	-AM2-1			
Duration	One sen	nester			
Course frequency	Winter s	semester			
Module language	English				
Prerequisites	Associa	ted basic module	is recommended		
Associated courses	One cou courses		ted from all advanced AIR		
Instructor	Depend	s on selected cour	se		
Examination	See syll	abus (varies by co	urse)		
Grading	See syll	abus (varies by co	urse)		
Learning outcomes	<ul> <li>deve Al ar</li> <li>dem unde prind mach robo visio syste</li> <li>anal</li> <li>gene prob cond</li> <li>deve and</li> </ul>	<ul> <li>understanding of the fundamental concepts, principles, and theories in AI and robotics, such as machine learning, data science, deep learning, robotics, natural language processing, computer vision, reinforcement learning, and control systems;</li> <li>analyze and find solutions to a given problem;</li> <li>generate novel solutions and approaches to problems based on a concept or a combination of concepts presented in this course;</li> <li>develop proficiency in using state-of-the-art AI and robotics tools and platforms; and</li> <li>effectively reflect upon their knowledge and experiences in an interdisciplinary context by identifying connections between different disciplines and applying them in a meaningful way.</li> </ul>			
	knowled navigati learning Student course d	<ul> <li>knowledge in up to three of the six fields of AI, robot navigation, deep learning, data science, machine learning, and computer vision.</li> <li>Students select one course from the advanced course offerings.</li> <li>The syllabus outlines the specific course content.</li> </ul>			
Teaching and learning					
Related programs		and Robotics			

5.8 Advanced Module 3 6 ECTS				
Recommended semester	3 <sup>rd</sup> semester	Total workload	180 hours	
Module number	1-M-AIR	-AM3-1		
Duration	One sen	nester		
Course frequency	Winters	semester		
Module language	English			
Prerequisites	Associa	ted basic module	is recommended	
Associated courses	One cou courses		ted from all advanced AIR	
Instructor	Depend	s on selected cou	rse	
Examination	See syll	abus (varies by co.	ourse)	
Grading	See syll	abus (varies by co	ourse)	
Learning outcomes Content	<ul> <li>deve Al ar</li> <li>dem unde prine mac robo visio syste</li> <li>anal</li> <li>gene prob conc</li> <li>deve and</li> <li>effece expecident</li> </ul>	<ul> <li>understanding of the fundamental concepts, principles, and theories in AI and robotics, such as machine learning, data science, deep learning, robotics, natural language processing, computer vision, reinforcement learning, and control systems;</li> <li>analyze and find solutions to a given problem;</li> <li>generate novel solutions and approaches to problems based on a concept or a combination of concepts presented in this course;</li> <li>develop proficiency in using state-of-the-art AI and robotics tools and platforms; and</li> <li>effectively reflect upon their knowledge and experiences in an interdisciplinary context by identifying connections between different disciplines and applying them in a meaningful</li> </ul>		
ountent	knowled navigati learning Student course d	<ul> <li>knowledge in up to three of the six fields of AI, robot navigation, deep learning, data science, machine learning, and computer vision.</li> <li>Students select one course from the advanced course offerings.</li> <li>The syllabus outlines the specific course content.</li> </ul>		
Teaching and learning				
Related programs		l and Robotics		

5.9 Learning in	Transfo	ormatio	n Project	12 ECTS	
Recommended semester	2 <sup>nd</sup> and 3 <sup>rd</sup> semester		Total workload	360 hours	
Module number		1-M-AIR-L	TP-1		
Duration		Two seme	sters		
Course frequency		Summer s	emester		
Module language		English			
Prerequisites			modules and Ke commended	y Qualifications Basic	
Associated courses		Transform	ative Learning P	roject	
Instructor(s)		1-2 professor(s) from any department who can supervise the projects and coaches/teaching assistants			
Examination		Project, sc	ientific paper, oi	presentation	
Grading		Pass/fail			
Learning outcomes	<ul> <li>Students are able to</li> <li>identify steps to solving a real-world research problem and design an action plan to implement these steps;</li> <li>develop and test a working prototype;</li> <li>critically evaluate and provide feedback on solution approaches from other student groups;</li> <li>explain and present the solution approach to the stakeholder(s) and peers; and</li> <li>assess/evaluate the outcome of the project and defend the development steps.</li> </ul>				
Content		The Learning in Transformation Project is an interdisciplinary scientific research project that focuses on practical learning experiences. The project aims to provide students with a scientific- based approach to solving real-world industrial, societal, or political problems faced by non-university stakeholders. The project encourages students to creatively apply their prior knowledge to solve these problems in groups. For further information see the syllabus.			
Teaching and learning	The module is set up as a mixture of learning units, discussion and supervision sessions, field trips, and a high proportion of independent work within student groups. Over the course of the two semesters, milestones help structure the project planning and assure that the group is on track and on time. They are further used to document the project and learning progress. For further information see the syllabus.				
Related programs		M.Sc. AI and Robotics			

5.10 Interdiscip	olinary M	/Iodule 1		6 ECTS	
Recommended semester	2 <sup>nd</sup> semes	ster	Total workload	180 hours	
Module number		2-M-IND-I	M1-1		
Duration		One semes	ster		
Course frequency		Summer s	emester		
Module language		English			
Prerequisites		None			
Associated courses			e must be selected fr olinary courses	om all	
Instructor		Depends o	n selected course		
Examination		See syllab	us (varies by course)		
Grading		Graded			
		<ul> <li>understand selected scientific approaches and methods in the social sciences and humanities;</li> <li>develop critical thinking and problem-solving skills and apply them to real-world problems;</li> <li>apply knowledge of social science and liberal arts theories to analyze and evaluate the impact of technology on society;</li> <li>analyze the social, ethical, legal, and cultural implications of technology using social science and liberal arts methodologies; and</li> <li>combine technological, social science, and liberal arts knowledge and methods to create novel technological solutions.</li> </ul>			
Content		In the interdisciplinary module, students develop an interdisciplinary perspective that complements their scientific core courses. Students select one course from the interdisciplinary course offerings. Courses are offered in the areas of design, social sciences, ethics and philosophy, law, and economics and business studies. The syllabus outlines the specific course content.			
Teaching and learning	g formats	See syllabus			
Related programs		M.Sc. Al and Robotics			

5.11 Interdisciplinary Module 2 6 ECTS					
Recommended semester	4 <sup>th</sup> semes	ter	Total workload	180 hours	
Module number		2-M-IND-I	M2-1		
Duration		One seme	ster		
Course frequency		Summer s	emester		
Module language		English			
Prerequisites		None			
Associated courses			e must be selecte blinary courses	d from all	
Instructor		Depends o	on selected course	9	
Examination		See syllab	ous (varies by cour	se)	
Grading		Graded			
		<ul> <li>understand selected scientific approaches and methods in the social sciences and humanities;</li> <li>develop critical thinking and problem-solving skills and apply them to real-world problems;</li> <li>apply knowledge of social science and liberal arts theories to analyze and evaluate the impact of technology on society;</li> <li>analyze the social, ethical, legal, and cultural implications of technology using social science and liberal arts methodologies; and</li> <li>combine technological, social science, and liberal arts knowledge and methods to create novel technological solutions.</li> </ul>			
Content		In the interdisciplinary module, students develop an interdisciplinary perspective that complements their scientific core courses. Students select one course from the interdisciplinary course offerings. Courses are offered in the areas of design, social sciences, ethics and philosophy, law, and economics and business studies. The syllabus outlines the specific course content.			
Teaching and learning	g formats	See syllabus			
Related programs		M.Sc. AI and Robotics			

5.12 Key Qualif	ication	Basic M	odule	6 ECTS	
Recommended semester	1 <sup>st</sup> semes	ter	Total workload	180 hours	
Module number	1	8-M-KQU-	KQB-1		
Duration		One seme	ster		
Course frequency		Winter sei	nester		
Module language		English			
Prerequisites		None			
Associated courses		Good Scientific Practice Project Management Communication All three courses must be completed.			
Instructor		Depends of	on the course		
Examination		Learning-	oriented assignme	ents	
Grading		Pass/fail			
Learning outcomes	<ul> <li>Students are able to</li> <li>understand basic principles of good scientific practice;</li> <li>identify different forms and situations of scientific misconduct and apply strategies to avoid them;</li> <li>discuss various project management techniques and tools;</li> <li>identify potential problems within teams and respond appropriately;</li> <li>understand communication forms and techniques and apply them appropriately to different situations;</li> <li>apply principles of intercultural communication; and</li> <li>communicate effectively in groups with individuals of different scientific or professional backgrounds.</li> </ul>				
Content		<i>Good Scientific Practice</i> Students learn the rules and values of responsible and ethical research. This includes proper handling of data, sources, and ideas of others as well as citation			

Related programs	M.Sc. AI and Robotics		
Teaching and learning formats	See Syllabus		
	The course specifically prepares students for the Learning in Transformation Project.		
	Students acquire communication techniques to communicate effectively in intercultural and interprofessional teams.		
	Communication		
	The course specifically prepares students for the Learning in Transformation Project.		
	Students learn basic project management tools and techniques and how to apply them correctly. This includes project planning, risk management, roles and associated tasks, team management, project monitoring, and evaluation.		
	Project Management		
	rules, forms of scientific misconduct and how to avoid them, and research ethics.		

5.13 Key Qualif	ication	Module	1	6 ECTS	
Recommended semester	2 <sup>nd</sup> semes	ster	Total workload	180 hours	
Module number		8-M-KQU-	KQ1-1		
Duration		One seme	ster		
Course frequency		Summer s	emester		
Module language		English			
Prerequisites		None			
Associated courses		ECTS poin	ts (usually 2-3 course	•	
		A total of 6 ECTS points must be earned from the available KQ courses.			
Instructor		Depends on selected course			
Examination		See syllabus (varies by course)			
Grading		Pass/fail			
Learning outcomes		<ul> <li>Students are able to</li> <li>apply key techniques and methodologies needed to work in an academic and professional environment;</li> <li>communicate effectively in foreign languages; and</li> <li>reflect on and extend their knowledge independently.</li> </ul>			
Content		In the key qualification module, students acquire academic and professional key qualifications. Students select two or three courses from the key qualifications course offerings. The syllabus outlines the specific course content.			
Teaching and learning formats		Courses are offered in weekly sessions or as block courses during the course-free period. The syllabus outlines specific course information.			
Related programs		M.Sc. AI and Robotics			

5.14 Key Qualif	ication I	Module 2		6 ECTS	
Recommended Semester	3 <sup>rd</sup> semes	ter	Total Workload	180 hours	
Module number		8-M-KQU	-KQ2-1		
Duration		One seme	ester		
Course frequency		Winter se	mester		
Module language		English			
Prerequisites		None			
Associated courses			-	s that provide a total of 6 ourses) per module.	
		A total of 6 ECTS points must be earned from the available KQ courses.			
Instructor		Depends on selected course			
Examination		See syllabus (varies by course)			
Grading		Pass/fail			
Learning outcomes		<ul> <li>Students are able to</li> <li>apply key techniques and methodologies needed to work in an academic and professional environment;</li> <li>communicate effectively in foreign languages; and</li> <li>reflect on and extend their knowledge independently.</li> </ul>			
Content	In the key qualification module, students acquire academic and professional key qualifications. Students select two or three courses from the key qualifications course offerings. The syllabus outlines the specific course content.				
Teaching and learning	Courses are offered in weekly sessions or as block courses during the course-free period. The syllabus outlines specific course information.				
Related programs		M.Sc. AI and Robotics			

5.15 Master's Thesis				24 ECTS	
Recommended semester	4 <sup>th</sup> semes	ster	Total workload	720 hours	
Module number		1-M-AIR-TH	HE-1	·	
Duration		One semes	ster		
Course frequency		Winter and	d Sommer semest	er	
Module language		English			
Prerequisites		None			
Associated courses		Master's C	Colloquium		
Instructor		Student se	elect the thesis ac	lvisor	
Examination		Thesis and	l oral exam		
Grading		Graded			
Learning outcomes		<ul> <li>Students are able to</li> <li>formulate a research question in AI and robotics, select the appropriate methodology and literature, and design an evaluation strategy;</li> <li>use scientific methods to propose an innovative solution to a complex problem;</li> <li>critically analyze and evaluate theories and approaches and reflect on their assumptions and limitations in an interdisciplinary context;</li> <li>integrate knowledge from different domains to create novel solutions to the research problem;</li> <li>independently plan a research project within a given time frame;</li> <li>apply the rules of good scientific practice to all parts of the research project; and</li> <li>structure and communicate research results in accordance with academic standards.</li> </ul>			
Content		The students select their research topics in coordination with their advisor. The students present their work during a research colloquium that takes place during the term.			
Teaching and learning	g formats	Independent research and colloquium See syllabus			
Related programs		M.Sc. Al and Robotics			
Netated programs		WI.SC. AI di			